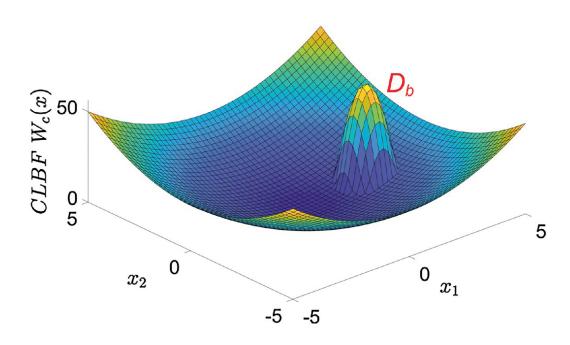


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Cover figure from "Handling bounded and unbounded unsafe sets in Control Lyapunov-Barrier function-based model predictive control of nonlinear processes" by Zhe Wu and Panagiotis D, found on pages 140-149 of this issue.



